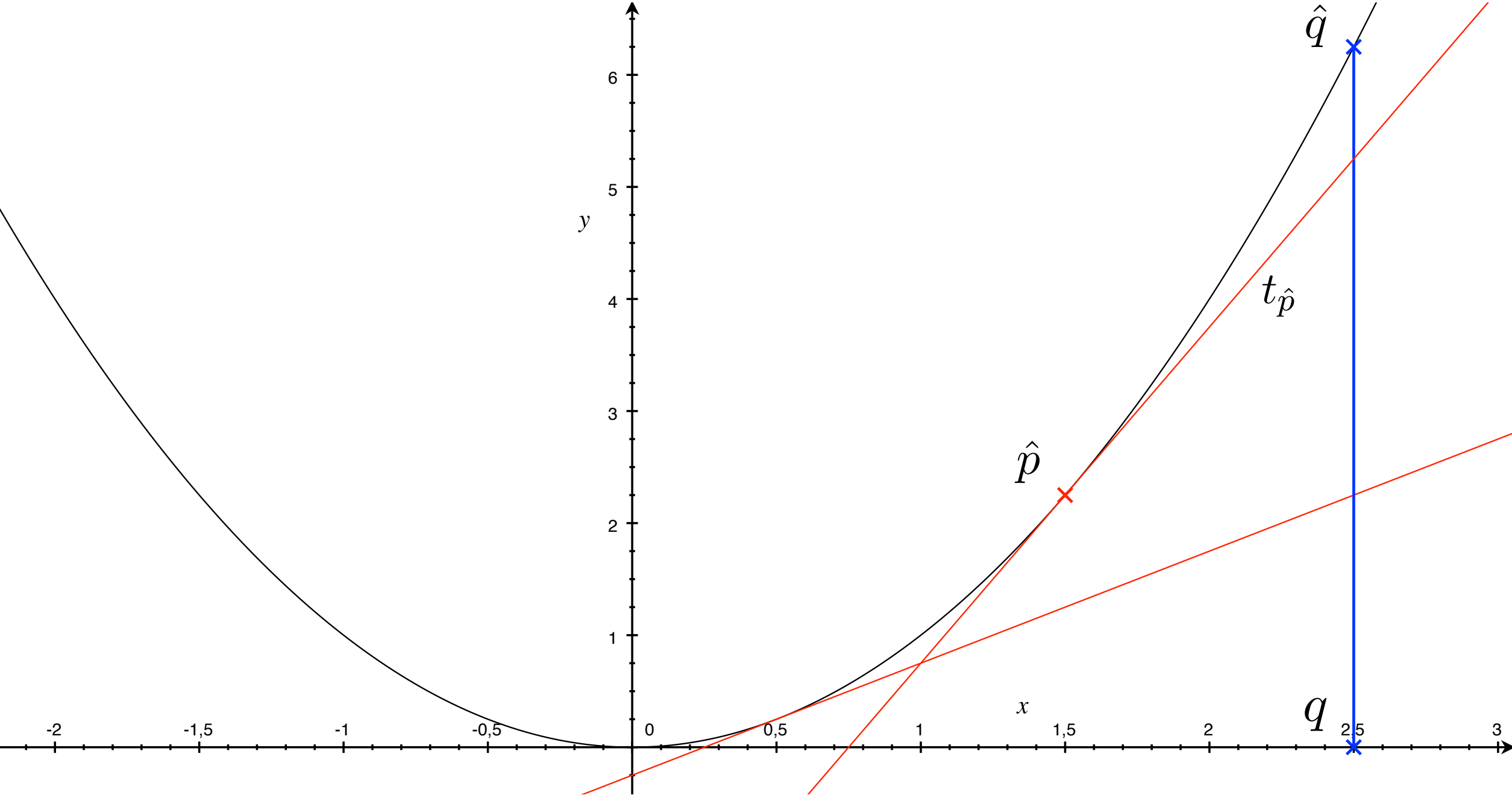
$\hat{q}$
$t_{\hat{p}}$
$\hat{p}$
q
y
x
6
5
4
3
2
1
-2
-1,5
-1
-0,5
0
0,5
1
1,5
2
2,5
3