## Lattice Paths with States, and

Counting Geometric Objects via Production Matrices
(a preliminary report on unproved results)

## Günter Rote Freie Universität Berlin

 ongoing joint work with Andrei Asinowski and Alexander Pilz
a non-crossing perfect matching

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the generalized double zigzag chain


## Lattice Paths with States

- Finite set of states $Q=\{\bullet, \circ, \llbracket, \square, \Delta, \ldots\}$
- For each $q \in Q$, a set $S_{q}$ of permissible steps $\left((i, j), q^{\prime}\right)$ : From point $(x, y)$ in state $q$, can go to $(x+i, y+j)$ in


Wanted: The number of paths from $(0,0)$ in state $q_{0}$ to $(n, 0)$ in state $q_{1}$ that don't go below the $x$-axis.

## Formula for Lattice Paths with States


$(i, j) \mapsto t^{i} u^{j}$


Conjecture: The number of paths from $(0,0)$ in state $q_{0}$ to $(n, 0)$ in state $q_{1}$ that don't go below the $x$-axis is

$$
\sim \text { const } \cdot\left(1 / t^{*}\right)^{n} \cdot n^{-3 / 2},
$$

where
(1) $A\left(t^{*}, u^{*}\right)$ has largest (Perron-Frobenius) eigenvalue 1.

$$
[\Longrightarrow \operatorname{det}(A(t, u)-I)=0]
$$

(2) $u^{*}>0$ is chosen such that the value $t^{*}>0$ that fulfills (1) is as large as possible. $\quad\left[\Longrightarrow \frac{\partial}{\partial u} \operatorname{det}(A(t, u)-I)=0\right]$

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under some obvious technical conditions:

- state graph is strongly connected
- no cycles in the lattice paths
- aperiodic
- Introduction. Point sets with many noncrossing $X$
- The lattice path formula with states (preview)
- Overview
- Example 1: Triangulations of a convex $n$-gon
- Production matrices
- Example 2: Noncrossing forests in a convex $n$-gon
- Example 3: Geometric graphs on the generalized double zigzag chain.
- Proof idea 1. Analytic combinatorics
- Proof idea 2. Random walk


## Triangulations of a convex $n$-gon



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## Triangulations of a convex $n$-gon

Triangulation of $n$-gon with last vertex of degree $d_{n}=d$
$\qquad$
Triangulation of $(n+1)$-gon with last vertex of degree

$$
\begin{array}{r}
d_{n+1}=2 \text { or } 3 \text { or } 4 \text { or } \ldots \text { or } d \text {, or } d+1 \\
\\
\quad \text { [ Hurtado \& Noy 1999 ] } \\
\text { "tree of triangulations" }
\end{array}
$$



## Triangulations of a convex $n$-gon

Triangulation of $n$-gon with last vertex of degree $d_{n}=d$

Triangulation of $(n+1)$-gon with last vertex of degree

$$
d_{n+1}=2 \text { or } 3 \text { or } 4 \text { or } \ldots \text { or } d \text {, or } d+1
$$



## triangulation <br> $\uparrow$ <br> lattice path

## Production matrices


count paths in
a layered graph

The answer is

$$
\left.\begin{array}{llll}
\text { is } \\
\left(\begin{array}{lll}
1 & 0 & 0
\end{array}\right. & \ldots
\end{array}\right) \underbrace{\left(\begin{array}{ccccc}
1 & 1 & 1 & 1 & \ldots \\
1 & 1 & 1 & 1 & \ldots \\
0 & 1 & 1 & 1 & \ldots \\
0 & 0 & 1 & 1 & \ldots \\
0 & 0 & 0 & 1 & \ldots \\
\vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right)}_{\text {the }} \text { "production matrix" } P
$$

## Production matrices for enumeration

were introduced by Emeric Deutsch, Luca Ferrari, and Simone Rinaldi (2005).
were used for counting noncrossing graphs for points in convex position:

Huemer, Seara, Silveira, and Pilz (2016)
Huemer, Pilz, Seara, and Silveira (2017)

| $\left(\begin{array}{ccccc}0 & 1 & 1 & 1 & \ldots \\ 1 & 0 & 1 & 1 & \ldots \\ 0 & 1 & 0 & 1 & \ldots \\ 0 & 0 & 1 & 0 & \ldots \\ 0 & 0 & 0 & 1 & \ldots \\ \vdots & \vdots & \vdots & \vdots & \ddots\end{array}\right)$ |
| :---: | :---: | :---: | :---: | :---: |
| matchings$\left(\begin{array}{cccccc}2 & 3 & 4 & 5 & \ldots \\ 1 & 2 & 3 & 4 & \ldots \\ 0 & 1 & 2 & 3 & \ldots \\ 0 & 0 & 1 & 2 & \ldots \\ 0 & 0 & 0 & 1 & \ldots \\ \vdots & \vdots & \vdots & \vdots & \ddots\end{array}\right)$ |\(\left(\begin{array}{ccccc}1 \& 1 \& 1 \& 1 \& ··· <br>

1 \& 3 \& 4 \& 5 \& ··· <br>
0 \& 1 \& 3 \& 4 \& ··· <br>
0 \& 0 \& 1 \& 3 \& ··· <br>
0 \& 0 \& 0 \& 1 \& ··· <br>
\vdots \& \vdots \& \vdots \& \vdots \& \ddots\end{array}\right)\)



Number of paths is preserved.

Shearing
$\rightarrow$ Dyck paths
$\rightarrow$ Catalan numbers



Number of paths is preserved.

## Example 2: Forests

$$
P=\left(\begin{array}{cccccc}
1 & 1 & 1 & 1 & 1 & \ldots \\
1 & 3 & 4 & 5 & 6 & \ldots \\
0 & 1 & 3 & 4 & 5 & \ldots \\
0 & 0 & 1 & 3 & 4 & \ldots \\
0 & 0 & 0 & 1 & 3 & \ldots \\
\vdots & \vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right)
$$

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0 & 0 & 0 & 1 & 3 & \ldots \\
\vdots & \vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right)
$$

Irregularities at the boundary can be ignored.

## Example 2: Forests

$\left(\begin{array}{llllll}1 & 1 & 1 & 1 & 1 & \ldots\end{array}\right)$ Irregularities at the boundary can be ignored.


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\end{array}\right)
$$

can be ignored.



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$\left(\begin{array}{llllll}1 & 1 & 1 & 1 & 1 & \ldots\end{array}\right)$ Irregularities at the boundary
$P=\left(\begin{array}{cccccc}1 & 3 & 4 & 5 & 6 & \ldots \\ 0 & 1 & 3 & 4 & 5 & \ldots \\ 0 & 0 & 1 & 3 & 4 & \ldots \\ 0 & 0 & 0 & 1 & 3 & \ldots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots\end{array}\right)$ can be ignored.



## Example 2: Forests

$$
P=\left(\begin{array}{cccccc}
1 & 1 & 1 & 1 & 1 & \ldots \\
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0 & 1 & 3 & 4 & 5 & \ldots \\
0 & 0 & 1 & 3 & 4 & \ldots \\
0 & 0 & 0 & 1 & 3 & \ldots \\
\vdots & \vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right) \quad \begin{aligned}
& \text { Irregularities at the boundary } \\
& \text { can be ignored. }
\end{aligned} \quad A=\left(\begin{array}{c|cc} 
& \bullet & \circ \\
\hline \bullet & t^{3}+t u^{-2} & t u \\
\circ & t u & t u^{-2}
\end{array}\right)
$$




## Solving for $t^{*}$ and $u^{*}$



## Solving for $t^{*}$ and $u^{*}$



Solving for $t^{*}$ and $u^{*}$


## Example 3: Geometric graphs


the generalized double zigzag chain [ Huemer, Pilz, and Silveira 2018]

$R=\left(\begin{array}{cccccc}1 & 1 & 1 & 1 & 1 & \ldots \\ 0 & 2 & 2 & 2 & 2 & \ldots \\ 0 & 0 & 2 & 2 & 2 & \ldots \\ 0 & 0 & 0 & 2 & 2 & \ldots \\ 0 & 0 & 0 & 0 & 2 & \ldots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots\end{array}\right), S=\left(\begin{array}{cccccc}0 & 0 & 0 & 0 & 0 & \ldots \\ 1 & 0 & 0 & 0 & 0 & \ldots \\ 0 & 1 & 0 & 0 & 0 & \ldots \\ 0 & 0 & 1 & 0 & 0 & \ldots \\ 0 & 0 & 0 & 1 & 0 & \ldots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots\end{array}\right)$
$P=R^{3}+S R^{2}+S(I+S) R+S(I+S)^{2}$

## Example 3: Geometric graphs

$P=R^{3}+S R^{2}+S(I+S) R+S(I+S)^{2}$




$$
A=\left(\begin{array}{c|cccc} 
& \bullet & \boldsymbol{■}_{1} & \boldsymbol{\varpi}_{2} & \boldsymbol{\varpi}_{3} \\
\hline \bullet & t\left(u+2 u^{2}+u^{3}\right) & 2 & 2 u & 2 u+2 u^{2} \\
\boldsymbol{\varpi}_{1} & 0 & u^{-1} & 2 & 0 \\
\boldsymbol{\varpi}_{2} & 0 & 0 & u^{-1} & 2 \\
\boldsymbol{■}_{3} & t & 0 & 0 & u^{-1}
\end{array}\right)
$$

## Proofs

Conjecture: The number of paths from $(0,0)$ in state $q_{0}$ to $(n, 0)$ in state $q_{1}$ that don't go below the $x$-axis is

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APPROACHES:
A) Analytic Combinatorics, "square-root-type" singularity
B) Probabilistic interpretation, random walk
C) Pedestrian, induction

## Proofs

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APPROACHES:
A) Analytic Combinatorics, "square-root-type" singularity Special case: One state. All steps are of the form $(1, j)$.
[ Banderier and Flajolet, 2002 ]
$\left[\operatorname{det}(A(t, u)-I)=t \cdot Q(u)-1=0, \quad Q^{\prime}(u)=0\right]$

## Proofs

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(3) Let $\vec{v}$ and $\vec{w}$ be left and right eigenvectors of $A(t, u)$ with eigenvalue 1. Then

$$
\vec{v} \cdot \frac{\partial}{\partial u} A(t, u) \cdot \vec{w}=0
$$

$(1) \wedge(2) \Leftrightarrow(1) \wedge(3)$. (linear algebra)
$(1) \Longrightarrow N_{(x, y), q} \leq v_{q} t^{-x} u^{-y}$ by easy induction.

## Random walk

Use entries $a_{q r}$ of $A=A(t, u)$ as "weights" for a random walk. What is the effect of $u$ in $t^{i} u^{j}$ ? Up-jumps $(j>0)$ are favored $(u>1)$ or penalized $(u<1)$ over down-jumps.
The weight of a path from $(0,0)$ to $(n, 0)$ is unaffected by $u$ ! Every path weight is multiplied by $t^{n}$.
$\left(\begin{array}{ccc}0.71 & 0.25 & 0.05 \\ 0.31 & 0.0 & 0.02\end{array}\right) \quad$ Use right eigenvector $\vec{w}$ to rescale $A=\left(\begin{array}{ccc}0.31 & 0.00 & 0.02 \\ 3.15 & 0.66 & 0.12\end{array}\right) \quad$ into probabilities: $p_{q r}=a_{q r} \frac{w_{r}}{w_{q}}$ $\begin{array}{lll}3.15 & 0.66 & 0.12\end{array} \rightarrow$ stochastic matrix
What does $\frac{\partial}{\partial u} A(t, u)$ mean? The expected vertical jump!
Step (8, 5): $\frac{\partial}{\partial u} t^{8} u^{5}=5 t^{8} u^{4} \Longrightarrow u \frac{\partial}{\partial u} t^{8} u^{5}=5 t^{8} u^{5}=5 a_{q r}$
"No-drift" condition: $\vec{v} \cdot\left(u \cdot \frac{\partial}{\partial u} A(t, u)\right) \cdot \vec{w}=0$ stationary distribution

## Local Limit Theorems

Prob[sum of $n$ i.i.d. random variables with mean 0 lies in some small region around 0$] \sim$ const $\cdot n^{-1 / 2}$
[Gnedenko ]
Needs to be adapted to sign-restricted case $(y \geq 0)$ and several states.

## Local Limit Theorems

$\operatorname{Prob}[$ sum of $n$ i.i.d. random variables with mean 0 lies in some small region around 0 ] $\sim$ const $\cdot n^{-1 / 2}$
[ Gnedenko ]
Needs to be adapted to sign-restricted case ( $y \geq 0$ ) and several states.
"Pedestrian" approach. Pioneered for a special case with 2 states in Asinowski and Rote (2018).

- $O\left(\left(1 / t^{*}\right)^{n}\right)$ by induction.
- $\Omega\left(\left(1 / t^{*}-\varepsilon\right)^{n}\right)$ for every $\varepsilon>0$, by induction.


## Extensions

- higher dimensions
- jumps $(i, j) \in \mathbb{R}^{2}$

