

# Using Redundancies to Find Errors

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**Abstract**—Programmers generally attempt to perform useful work. If they performed an action, it was because they believed it served some purpose. Redundant operations violate this belief. However, in the past redundant operations have been typically regarded as minor cosmetic problems rather than serious errors. This paper demonstrates that in fact many redundancies are as serious as traditional hard errors (such as race conditions or null pointer dereferences). We experimentally test this idea by writing and applying five redundancy checkers to a number of large open source projects, finding many errors. We then show that even when redundancies are harmless they strongly correlate with the presence of traditional hard errors. Finally we show how flagging redundant operations gives a way to detect mistakes and omissions in specifications. For example, a locking specification that binds shared variables to their protecting locks can use redundancies to detect missing bindings by flagging critical sections that include no shared state.

**Index Terms**—Extensible compilation, error detection, program redundancy, software quality.

## I. INTRODUCTION

Programming languages have long used the fact that many high-level conceptual errors map to low-level type errors. This paper demonstrates the same mapping in a different direction: many high-level conceptual errors also map to low-level redundant operations. With the exception of a few stylized cases, programmers are generally attempting to perform useful work. If they performed an action, it was because they believed it served some purpose. Spurious operations violate this belief and are likely errors. However, in the past redundant operations have been typically regarded as merely cosmetic problems, rather than serious mistakes. Evidence for this perception is that to the best of our knowledge the many recent error checking projects focus solely on hard errors such as null pointer dereferences or failed lock releases, rather than redundancy checking [2], [4], [5], [9], [13], [23], [25].

We experimentally demonstrate that in fact many redundancies signal mistakes as serious as traditional hard errors. For example, impossible Boolean conditions can signal mistaken expressions; critical sections without shared states can signal the use of the wrong variable; variables written but not read can signal an unintentionally lost result. Even when harmless, these redundancies signal conceptual confusion, which we would also expect to correlate with hard errors such as deadlocks, null pointer dereferences, etc.

In this paper we use redundancies to find errors in three ways: (1) by writing checkers that automatically flag redundancies, (2) using these errors to predict non-redundant errors (such as null pointer dereferences), and (3) using redundancies

to find incomplete program specifications. We discuss each below.

We wrote five checkers that flagged potentially dangerous redundancies: (1) idempotent operations, (2) assignments that were never read, (3) dead code, (4) conditional branches that were never taken, and (5) redundant NULL-checks. The errors found would largely be missed by traditional type systems and checkers. For example, as Section II shows, assignments of variables to themselves can signal mistakes, yet such assignments will type check in any common programming language we know of.

Of course, some legitimate actions cause redundancies. Defensive programming may introduce “unnecessary” operations for robustness; debugging code, such as assertions, can check for “impossible” conditions; and abstraction boundaries may force duplicate calculations. Thus, to effectively find errors, our checkers must separate such redundancies from those induced by high-level confusion.

The technology behind the checkers is not new. Optimizing compilers use redundancy detection and elimination algorithms extensively to improve code performance. One contribution of our work is the realization that these analyses have been silently finding errors since their invention.

We wrote our redundancy checkers in the *MC* extensible compiler system [15], which makes it easy to build system-specific static analyses. Our analyses do not depend on an extensible compiler, but it does make it easier to prototype and perform focused suppression of false positive classes.

We evaluated how effective flagging redundant operations is at finding dangerous errors by applying the above five checkers to three open source software projects: Linux, OpenBSD and PostgreSQL. These are large, widely-used source code bases (we check 3.3 million lines of them) that serve as a known experimental base. Because they have been written by many people, they are representative of many different coding styles and abilities.

We expect that redundancies, even when harmless, strongly correlate with hard errors. Our relatively uncontroversial hypothesis is that confused or incompetent programmers tend to make mistakes. We experimentally test this hypothesis by taking a large database of hard Linux errors that we found in prior work [8] and measure how well redundancies predict these errors. In our experiments, files that contain redundancies are roughly 45% to 100% more likely to have traditional hard errors compared to those drawn by chance. This difference holds across the different types of redundancies.

Finally, we discuss how traditional checking approaches

based on annotations or specifications can use redundancy checks as a safety net to find missing annotations or incomplete specifications. Such specification mistakes commonly map to redundant operations. For example, assume we have a specification that binds shared variables to locks. A missed binding will likely lead to redundancies: a critical section with no shared state and locks that protect no variables. We can flag such omissions because we know that every lock should protect some shared variable and that every critical section should contain some shared state.

This paper makes four contributions:

- 1) The idea that redundant operations, like type errors, commonly flag serious correctness errors.
- 2) Experimentally validating this idea by writing and applying five redundancy checkers to real code. The errors found often surprised us.
- 3) Demonstrating that redundancies, even when harmless, strongly correlate with the presence of traditional hard errors.
- 4) Showing how redundancies provide a way to detect dangerous specification omissions.

The main caveat with our approach is that the errors we count might not be errors since we were examining code we did not write. To counter this, we only diagnosed ones that we were reasonably sure about. We have had close to three years of experience with Linux bugs, so we have reasonable confidence that our false positive rate of bugs that we diagnose, while non-zero, is probably less than 5%.

In addition, some of the errors we diagnose are not traditional “hard errors”—they by themselves would probably not cause system crashes or security breaches. Rather, they are nonsensical redundancies that in our opinion result in unnecessary complexity and confusion. So the diagnosis of these errors involve personal judgments that may not be shared by all readers. Although they are not as serious as hard errors, we think they should nevertheless be fixed in order to improve program clarity and readability.

Sections II through VI present the five checkers. Section VII measures how well these redundant errors correlate with and predict traditional hard errors. Section VIII discusses how to check for completeness using redundancies. Section IX discusses related work. Finally, Section X concludes.

## II. IDEMPOTENT OPERATIONS

System	Bugs	Minor	False
Linux 2.4.5-ac8	7	6	3
OpenBSD 3.2	2	6	8
PostgreSQL	0	0	0

TABLE I

BUGS FOUND BY THE IDEMPOTENT CHECKER IN LINUX VERSION 2.4.5-AC8, OPENBSD 3.2, AND POSTGRESQL 7.2.

The checker in this section flags idempotent operations where a variable is: (1) assigned to itself ( $x = x$ ), (2) divided by itself ( $x / x$ ), (3) bitwise or’d with itself ( $x | x$ ) or (4)

bitwise and’d with itself ( $x \& x$ ). The checker is the simplest in the paper (it requires about 10 lines of code in our system). Even so, it found several interesting cases where redundancies signal high-level errors. Four of these were apparent typos in variable assignments. The clearest example was the following Linux code, where the programmer makes a mistake while copying structure `sa` to `da`:

```
/* linux2.4.1/net/appletalk/aarp.c:aarp_rcv */
else { /* We need to make a copy of the entry. */
    da.s_node = sa.s_node;
    da.s_net = da.s_net;
```

This is a good example of how redundancies catch cases that type systems miss. This code — an assignment of an integer variable to itself — will type check in all common languages we know of, yet clearly contains an error. Two of the other errors in Linux were caused by integer overflow (or’ing an 8-bit variable by a constant that only had bits set in the upper 16 bits) which was optimized away by the `gcc` frontend. The final one in Linux was caused by an apparently missing conversion routine. The code seemed to have been tested only on a machine where the conversion was unnecessary, which prevented the tester from noticing the missing routine.

The two errors we found in OpenBSD are violations of the ANSI C standard. They both lie in the same function in the same source file. We show one of them below:

```
1 /* openbsd3.2/sys/kern/subr_userconf.c:userconf_add */
2 for (i = 0; i < pv_size; i++) {
3     if (pv[i] != -1 && pv[i] >= val)
4         pv[i] = pv[i]++; /* error */
5 }
```

The error occurs at line 4, and is detected with the help of the code canonicalization algorithm in the `xgcc` front end that translates this statement into:

```
pv[i] = pv[i]; /* redundant */
pv[i]++;
```

The ANSI C standard (Section 6.3) stipulates that “between the previous and next sequence point an object shall have its stored value modified at most once by the evaluation of an expression.” It is mere coincidence that `gcc` chooses to implement the side-effects of `pv[i]++` after that of the assignment itself. In fact, the Compaq C compiler<sup>1</sup> evaluates `pv[i]++` first and stores the *old* value back to `pv[i]`, causing the piece of code to fail in a non-obvious way. We tested four C compilers by different vendors on different architectures<sup>2</sup>. None of them issued a warning on this illegal statement.

The minor errors were operations that seemed to follow a nonsensical but consistent coding pattern, such as adding 0 to a variable for typographical symmetry with other non-zero additions such as the following

<sup>1</sup>Compaq C V6.3-129 (dtk) on Compaq Tru64 UNIX V5.0A (Rev. 1094).

<sup>2</sup>Sun Workshop 6 update 2, GNU GCC 3.2.1, Compaq C V6.3-129, and MS Visual Studio .NET.

```

/* linux2.4.5-ac8/drivers/video/riva/riva_hw.c:
nv4CalcArbitration */
nvclks += 1;
nvclks += 1;
nvclks += 1;
if (mp_enable)
    mclks+=4;
nvclks += 0; /* suspicious, is it a typo or
should it really be "+=1"? */

```

Curiously, each of the eleven false positives we found was annotated with a comment explaining why the redundant operation was being done. This gives evidence for our belief that programmers regard redundancy as somewhat unusual.

Macros are the main source of false positives. They represent logical operations that may not map to concrete actions. For example, networking code contains many calls of the form “`x = ntohs(x)`” used to reorder the bytes in variable `x` in a canonical “network order” so that a machine receiving the data can unpack it appropriately. However, on machines on which the data is already in network order, the macro will expand to nothing, resulting in code that will simply assign `x` to itself. To suppress these false positives, we modified the preprocessor to note which lines contain macros — we simply ignore warnings on these lines.

### III. REDUNDANT ASSIGNMENTS

System	Bugs	False	Uninspected
Linux 2.4.5-ac8	129	26	1840
OpenBSD 3.2	63	36	117
PostgreSQL 7.2	37	10	0

TABLE II

BUGS FOUND BY THE REDUNDANT ASSIGNMENT CHECKER IN LINUX VERSION 2.4.5-AC8, OPENBSD 3.2, AND POSTGRESQL 7.2.

The checker in this section flags cases where a value assigned to a variable is not subsequently used. The checker tracks the lifetime of variables using a simple intraprocedural analysis. At each assignment it follows the variable forward on all paths. It emits an error message if the variable is not read on any path before either exiting scope or being assigned another value. As we show, in many cases such lost values signal real errors, such as control flow following unexpected paths, results computed but not returned, etc.

The checker found thousands of redundant assignments in the three systems we checked. Since it was so effective, we minimized the chance of false positives by radically restricting the variables it would follow to non-global and non-volatile ones that were not aliased in any way (i.e. local variables that never had their addresses taken).

Most of the checker code deals with differentiating the errors into three classes, which it ranks in the following order:

- 1) Variables assigned values that are not read, and which are never subsequently reassigned. Empirically, these errors tend to be the most serious, since they flag unintentionally lost results.
- 2) Variables assigned a non-constant value that are not read, and which are subsequently reassigned. These are

also commonly errors, but tend to be less severe. False positives in this class tend to come from assigning a return value from a function call to a dummy variable that is ignored, which is prevalent in PostgreSQL. Fortunately, such variables tend to share a consistent naming pattern (e.g., they are commonly prefixed with double underscores (`_`) in PostgreSQL) and therefore can be easily suppressed with `grep`. In presenting bug counts in Table II, we do not count warnings that are so suppressed.

- 3) Variables assigned a constant and then reassigned other values without being read. These are frequently due to defensive programming, where the programmer always initializes a variable to some safe value (most commonly: `NULL`, `0`, `0xffffffff`, and `-1`) but does not read it before redefinition. We track the initial value and emit it when reporting the error so that messages with a common defensive value can be easily filtered out. Again, we do not count filtered messages in Table II.

**Suppressing false positives.** As with many redundant checkers, macros and defensive programming cause most false positives. To minimize the impact of macros, the checker does not track variables killed or generated within them. Its main remaining vulnerability are values assigned and then passed to debugging macros that are turned off:

```

x = foo->bar;
DEBUG("bar = %d", x);

```

Typically there are a small number of such debugging macros, which we manually turn back on by modifying the header file in which they are defined.

We use ranking to minimize the impact of defensive programming. Redundant operations that can be errors when done within the span of a few lines can be robust programming practice when separated by 20 lines. Thus we rank reported errors based on (1) the line distance between the assignment and reassignment and (2) the number of conditional branches on the path. Close errors are most likely; farther ones arguably defensive programming.

**The errors.** This checker found more errors than all the others we have written combined. There were two interesting error patterns that showed up as redundant assignments: (1) variables whose values were (unintentionally) discarded and (2) variables whose values were not used because of surprising control flow (e.g., an unexpected return).

---

```

1 /* linux2.4.5-ac8/net/decnet/af_decnet.c:dn_wait_run */
2 do {
3     ...
4     if (signal_pending(current)) {
5         err = -ERESTARTSYS; /* BUG: lost value */
6         break;
7     }
8     ...
9 } while(scp->state != DN_RUN);
10 return 0; /* should be "return err" here */

```

---

Fig. 1. Lost return value caught by flagging the redundant assignment to `err`.

---

```

1 /* linux2.4.1/net/atm/lec.c:lec_addr_delete: */
2 for(entry=priv->lec_arp_tables[i];
3     entry != NULL;
4     entry=next) { /* BUG: never reached */
5     next = entry->next;
6     if (...) {
7         lec_arp_remove(priv->lec_arp_tables, entry);
8         kfree(entry);
9     }
10    lec_arp_unlock(priv);
11    return 0;
12 }

```

---

Fig. 2. A single-iteration loop caught by flagging the redundant assignment `next = entry->next`. The assignment appears to be read in the loop iteration statement (`entry = next`) but it is dead code, since the loop always exits after a single iteration. The logical result will be that if the entry the loop is trying to delete is not the first one in the list, it will not be deleted.

---

```

/* linux2.4.5-ac8/fs/nfs/unistr.c:nfs_collate_names */
for (cnt = 0; cnt < min(name1_len, name2_len); ++cnt) {
    c1 = le16_to_cpu(*name1++);
    c2 = le16_to_cpu(*name2++);
    if (ic) {
        if (c1 < upcase_len)
            c1 = le16_to_cpu(upcase[c1]);
        if (c2 < upcase_len)
            c2 = le16_to_cpu(upcase[c2]);
    }
    /* [META] stray terminator! */
    if (c1 < 64 && legal_ansi_char_array[c1] & 8);
        return err_val;
    if (c1 < c2)
        return -1;
    ...

```

---

Fig. 3. Catastrophic return caught by the redundant assignment to `c2`. The last conditional is accidentally terminated because of a stray statement terminator (“;”) at the end of the line, causing the routine to always return `err_val`.

The majority of the errors (126 of the 129 diagnosed ones) fall into the first category. Figure 1 shows a representative example from Linux. Here, if the function `signal_pending` returns true (a signal is pending to the current process), an error code is set (`err = -ERESTARTSYS`) and the code breaks out of the enclosing loop. The value in `err` must be passed back to the caller so that it will retry the system call. However, the code always returns 0 to the caller, no matter what happens inside the loop. This will lead to an insidious error: the code usually works but, occasionally, it will abort but return a success code, causing the client to assume that the operation happened.

There were numerous similar errors on the caller side where the result of a function was assigned to a variable but then ignored rather than being checked. The fact that logically the code contains errors is readily flagged by looking for variables assigned but not used.

The second class contains three diagnosed errors that comes from calculations aborted by unexpected control flow. Figure 2 gives one example from Linux: here all paths through a loop end in a return, wrongly aborting the loop after a single

---

```

/* linux2.4.1/net/ipv6/raw.c:rawv6_getsockopt */
switch (optname) {
case IPV6_CHECKSUM:
    if (opt->checksum == 0)
        val = -1;
    else
        val = opt->offset;
    /* BUG: always falls through */
default:
    return -ENOPROTOOPT;
}
len=min(sizeof(int),len);
...

```

---

Fig. 4. Unintentional switch “fall through” causing the code to always return an error. This maps to the low-level redundancy that the value assigned to `val` is never used.

iteration. This error is caught by the fact that an assignment used to walk down a linked list is never read because the loop iterator that would do so is dead code. Figure 3 shows a variation on the theme of unexpected control flow. Here an `if` statement has an extraneous statement terminator at its end, making the subsequent `return` to be always taken. In these cases, a coding mistake caused “dangling assignments” that were not used. This fact allows us to flag such bogus structures even when we do not know how control flows in the code. It is the the presence of these errors that has led us to write the dead-code checker in the next section.

Reassigning values is typically harmless, but it does signal fairly confused programmers. For example:

---

```

/* linux2.4.5-ac8/drivers/net/wan/sdla_x25.c:
    alloc_and_init_skb_buf */

```

```

struct sk_buff *new_skb = *skb;
new_skb = dev_alloc_skb(len + X25_HRDHDR_SZ);

```

where `new_skb` is assigned the value `*skb` but then immediately reassigned another allocated value. A different case shows a potential confusion about how C’s iteration statement works:

---

```

/* linux2.4.5-ac8/drivers/scsi/scsi.c:
    scsi_bottom_half_handler */
SCnext = SCpnt->bh_next;
for (; SCpnt; SCpnt = SCnext) {
    SCnext = SCpnt->bh_next;

```

Note that the variable `SCnext` is assigned and then immediately reassigned in the loop. The logic behind this decision remains unclear.

**The most devious error.** A few of the values reassigned before being used were suspicious lost values. One of the worst (and most interesting) was from a commercial system which had the equivalent of the following code:

```

c = p->buf[0][3];
c = p->buf[0][3];

```

At first glance this seems like a harmless obvious copy-and-paste error. It turned out that the redundancy flags a much more devious bug. The array `buf` actually pointed to a “memory mapped” region of kernel memory. Unlike normal memory, reads and writes to this region cause the CPU to issue I/O commands to a hardware device. Thus, the reads are not idempotent, and the two of them in a row rather than just

one can cause very different results to happen. However, the above code does have a real (but silent) error — in the variant of C that this code was written, pointers to device memory must be declared as “volatile.” Otherwise the compiler is free to optimize duplicate reads away, especially since in this case there were no pointer stores that could change their values. Dangerously, in the above case `buf` was declared as a normal pointer rather than a volatile one, allowing the compiler to optimize as it wished. Fortunately the error had not been triggered because the GNU C compiler that was being used had a weak optimizer that conservatively did not optimize expressions that had many levels of indirection. However, the use of a more aggressive compiler or a later version of `gcc` could have caused this extremely difficult to track down bug to surface.

#### IV. DEAD CODE

System	Bugs	False
Linux 2.4.5-ac8	66	26
OpenBSD 3.2	11	4
PostgreSQL 7.2	0	0

TABLE III

BUGS FOUND BY THE DEAD CODE CHECKER ON LINUX VERSION 2.4.5-AC8, OPENBSD 3.2, AND POSTGRESQL 7.2.

The checker in this section flags dead code. Since programmers generally write code to run it, dead code catches logical errors signaled by false beliefs that unreachable code can execute.

```

1 /* linux2.4.1/drivers/char/rio/rioparam.c:RIOParam */
2 if (retval == RIO_FAIL) {
3   rio_spin_unlock_irqrestore(&PortP->portSem, flags);
4   pseterr(EINTR); /* BUG: returns */
5   func_exit();
6   return RIO_FAIL;
7 }

```

Fig. 5. Unexpected return: The call `pseterr` is a macro that returns its argument value as an error. Unfortunately, the programmer does not realize this and inserts subsequent operations, which are flagged by our dead code checker. There were many other similar misuses of the same macro.

The core of the dead code checker is a straightforward mark-and-sweep algorithm. For each routine it (1) marks all blocks reachable from the routine’s entry node and (2) traverses all blocks in the routine, flagging any that are not marked. The checker has three modifications to this basic algorithm. First, it truncates all paths that reach functions that would not return. Examples include “panic,” “abort” and “BUG” which are used by Linux to signal a terminal kernel error and reboot the system — code dominated by such calls cannot run. Second, we suppress error messages for dead code caused by constant conditions involving macros or the `sizeof` operator, such as

```

1 /* linux2.4.1/drivers/scsi/53c7,8xx.c:
2   return_outstanding_commands */
3 for (c = hostdata->running_list; c;
4      c = (struct NCR53c7x0_cmd *) c->next) {
5   if (c->cmd->SCp.buffer) {
6     printk (". . .");
7     break;
8   } else {
9     printk ("Duh? . . .");
10    break;
11  }
12  /* BUG: cannot be reached */
13  c->cmd->SCp.buffer =
14    (struct scatterlist *) list;
15  ...

```

Fig. 6. Broken loop: the first if-else statement of the loop contains a break on both paths, causing the loop to always abort, without ever executing the subsequent code it contains.

```

1 /* linux2.4.5-ac8/net/decnet/dn_table.c:
2   dn_fib_table_lookup */
3 for(f = dz_chain(k, dz); f; f = f->fn_next) {
4   if (!dn_key_leq(k, f->fn_key))
5     break;
6   else
7     continue;
8
9   /* BUG: cannot be reached */
10  f->fn_state |= DN_S_ACCESSED;
11
12  if (f->fn_state & DN_S_ZOMBIE)
13    continue;
14  if (f->fn_scope < key->scope)
15    continue;

```

Fig. 7. Useless loop body: similarly to Figure 6 this loop has a broken if-else statement. One branch aborts the loop, the other uses C’s `continue` statement to skip the body and begin another iteration.

```

/* case 1: debugging statement that is turned 'off' */
#define DEBUG 0
if (DEBUG) printf("in foo");
/* case 2: gcc converts the condition to 0
on 32-bit architectures */
if (sizeof(int) == 64)
  printf("64 bit architecture\n");

```

The former frequently signals code “commented out” by using a false condition, while the latter is used to carry out architecture dependent operations. We also annotate error messages when the flagged dead code is only a `break` or `return`. These are commonly a result of defensive programming. Finally, we suppress dead code in macros.

Despite its simplicity, dead code analysis found a high number of clearly serious errors. Three of the errors caught by the redundant assignment checker are also caught by the dead code detector: (1) the single iteration loop in Figure 2, (2) the mistaken statement terminator in Figure 3, and (3) the unintentional fall through in Figure 4.

Figure 5 gives the most frequent copy-and-paste error. Here the macro “`pseterr`” has a `return` statement in its definition, but the programmer does not realize it. Thus, at all

---

```

1  /* openbsd3.2/sys/dev/pci/bktr/bktr_core.c:tuner_ioctl */
2  unsigned temp;
3  ...
4  temp = tv_channel( bktr, (int)*(unsigned long *)arg );
5  if ( temp < 0 ) { /* gcc frontend turns this into 0 */
6      /* BUG: cannot be reached */
7      temp_mute( bktr, FALSE );
8      return( EINVAL );
9  }
10 *(unsigned long *)arg = temp;

```

---

Fig. 8. Unsigned variable tested for negativity.

seven call sites that use the macro, there is dead code after the macro that the programmer intended to have executed.

Figure 6 gives another common error — a single-iteration loop that always terminates because it contains an if-else statement that breaks out of the loop on both branches. It is hard to believe that this code was ever tested. Figure 7 gives a variation on this, where one branch of the if statement breaks out of the loop but the other uses C’s continue statement, which skips the rest of the loop body. Thus, none of the code thereafter can be executed.

Type errors can also result in dead code. Figure 8 shows an example from OpenBSD. Here the function tv\_channel returns -1 on error, but since temp is an unsigned variable, the error handling code in the true branch of the if statement is never executed. An obvious fix is to declare temp as int. As before, none of the four compilers we tested warned about this suspicious typing mistake.

## V. REDUNDANT CONDITIONALS

System	Bugs	False	Uninspected
Linux 2.4.5-ac8	49	52	169
OpenBSD 3.2	64	33	316
PostgreSQL 7.2	0	0	0

TABLE IV

BUGS FOUND BY THE REDUNDANT CONDITIONALS CHECKER IN LINUX 2.4.5-AC8, OPENBSD 3.2, POSTGRESQL 7.2.

The checker in this section uses path-sensitive analysis to detect redundant (always true or always false) conditionals in branch statements such as if, while, switch, and etc. They cannot affect the program state or control flow. Thus, their presence is a likely indicator of errors. To avoid double reporting bugs found in the previous section, we only flag non-constant conditional expressions that are not evaluated by the dead code checker.

The implementation of the checker uses the false path pruning (FPP) feature in the xgcc system [15]. FPP was originally designed to eliminate false positives from infeasible paths. It prunes a subset of logically inconsistent paths by keeping track of assignments and conditionals along the way. The implementation of FPP consists of three separate modules, each keeping track of one class of program properties as described below:

---

```

1  /* linux2.4.5-ac8/fs/fat/inode.c */
2  error = 0;
3  if (!error) { /* causes unnecessary code complexity */
4      sbi->fat_bits = fat32 ? 32 :
5          (fat ? fat :
6          (sbi->clusters > MSDOS_FAT12 ? 16 : 12));

```

---

Fig. 9. Nonsensical programming style: the check at line 3 is clearly redundant.

- 1) The first module maintains a mapping from variables to integer constants. It tracks assignments (e.g. `x = 1;` `x = x * 2;`) and conditional branch statements (e.g. `if (x == 5) { ... }`) along each execution path to derive variable-constant bindings.
- 2) The second module keeps track of a known set of predicates that must hold true along the current program path. These predicates are collected from conditional branches (e.g. in the true branch of `if (x != NULL)` `{ ... }`, we will collect `x != NULL` into the known predicate set), and they will be used later to test the validity of subsequent control predicates (e.g. if we encounter `if (x != NULL)` later in the program, we will prune the `else` branch). Note if the value of variable `x` is killed (either directly by assignments or indirectly through pointers), we remove any conditional in the known predicate set that references `x`.
- 3) The third module keeps track of constant bounds of variables. We derive these bounds from conditional statements. For example, in the true branch of `if (x <= 5)`, we enter 5 as `x`’s upper bound. We prune paths that contradict with the recorded bound information (e.g. the true branch of `if (x > 7)`).

These three simple modules were able to capture enough information that allows us to find interesting errors in Linux and OpenBSD.

With FPP, the checker works as follows: for each function, it traverses the its control flow graph (CFG) with FPP and marks all reachable CFG edges. At the end of the analysis, it emits conditionals associated to untraversed ones as errors.

Macros and concurrency are the two major sources of false positives. To suppress those, we discard warnings that take place within macros, and ignore conditionals that involve global, static or volatile variables whose values might be changed by another thread.

The checker is able to find hundreds of redundant conditionals in Linux and OpenBSD. We classify them into three major categories which we describe below.

The first class of errors, which are the least serious of the three, are labeled as “nonsensical programming style.” Figure 9 shows a representative example from Linux 2.4.5-ac8. The if statement at line 3 is clearly redundant and leaves one to wonder about the purpose of such a check. These errors, although harmless, signal a confused programmer. The latter conjecture is supported by the statistical analysis described in section VII.

Figure 10 shows a more problematic case. The second if

---

```

1 /* linux2.4.5-ac8/drivers/net/wan/sbni.c:sbni_ioctl */
2 slave = dev_get_by_name(tmpstr);
3 if(!(slave && slave->flags & IFF_UP &&
4   dev->flags & IFF_UP))
5 {
6   ... /* print some error message, back out */
7   return -EINVAL;
8 }
9 if (slave) { ... }
10 /* BUG: !slave is impossible */
11 else {
12   ... /* print some error message */
13   return -ENOENT;
14 }

```

---

Fig. 10. Nonsensical programming style: the check of `slave` at line 9 is guaranteed to be true and also notice the difference in return value.

---

```

1 /* linux2.4.5-ac8/drivers/net/tokenring/smctr.c:
2   smctr_rx_frame */
3 while((status = tp->rx_fcb_curr[queue]
4   ->frame_status) != SUCCESS)
5 {
6   err = HARDWARE_FAILED;
7   ... /* large chunk of apparent recovery code,
8     with no updates to err */
9   if (err != SUCCESS)
10    break;
11 }

```

---

Fig. 11. Redundant conditional that suggests a serious program error.

statement is redundant because the first one has already taken care of the case where `slave` is false. The fact that a different error code is returned signals a possible bug in this code.

The second class of errors are again seemingly harmless on the surface, but when we give a more careful look at the surrounding code, we often find serious errors. The `while` loop in Figure 11 is obviously trying to recover from hardware errors encountered when reading network packets. But since the variable `err` is not updated in the loop body, it would never become `SUCCESS`, and thus the loop body will never be executed more than once, which is suspicious. This signals

---

```

1 /* linux2.4.1/drivers/fc/iph5526.c:
2   rscn_handler */
3 if ((login_state == NODE_LOGGED_IN) ||
4   (login_state == NODE_PROCESS_LOGGED_IN)) {
5   ...
6 }
7 else
8 if (login_state == NODE_LOGGED_OUT)
9   tx_adisc(fi, ELS_ADISC, node_id,
10    OX_ID_FIRST_SEQUENCE);
11 else
12 /* BUG: redundant conditional */
13 if (login_state == NODE_LOGGED_OUT)
14   tx_logi(fi, ELS_PLOGI, node_id);

```

---

Fig. 12. Redundant conditionals that signal errors: a conditional expression being placed in the `else` branch of another identical one.

---

```

1 /* linux2.4.5-ac8/drivers/scsi/qla1280.c:
2   qla1280_putq_t */
3 srb_p = q->q_first;
4 while (srb_p )
5   srb_p = srb_p->s_next;
6
7 if (srb_p) { /* BUG: this branch is never taken*/
8   sp->s_prev = srb_p->s_prev;
9   if (srb_p->s_prev)
10    srb_p->s_prev->s_next = sp;
11   else
12    q->q_first = sp;
13   srb_p->s_prev = sp;
14   sp->s_next = srb_p;
15 } else {
16   sp->s_prev = q->q_last;
17   q->q_last->s_next = sp;
18   q->q_last = sp;
19 }

```

---

Fig. 13. A serious error in a linked list insertion implementation: `srb_p` is always null after the `while` loop (which appears to be checking the wrong Boolean condition).

a possible error where the programmer forgets to update `err` in the large chunk of recovery code in the loop. This bug would be difficult to detect by testing, because it is in an error handling branch that is only executed when the hardware fails in a certain way.

The third class of errors are clearly serious bugs. Figure 12 shows an example from Linux 2.4.5-ac8. As we can see, the second and third `if` statements carry out entirely different actions on identical conditions. Apparently, the programmer has cut-and-pasted the conditional without changing one of the two `NODE_LOGGED_OUT`s into a more likely fourth possibility: `NODE_NOT_PRESENT`.

Figure 13 shows another serious error. The author obviously wanted to insert `sp` into a doubly-linked list that starts from `q->q_first`, but the `while` loop clearly does nothing other than setting `srb_p` to `NULL`, which is nonsensical. The checker detects this error by inferring that the ensuing `if` statement is redundant. An apparent fix is to replace the `while` condition (`srb_p`) with (`srb_p && srb_p->s_next`). This bug can be dangerous and hard to detect, because it quietly discards everything that was in the original list and constructs a new one with `sp` as its sole element. As a matter of fact, the same error is still present in the latest stable 2.4.20 release of the Linux kernel source as of this writing.

## VI. REDUNDANT NULL-CHECKS

The checker described in this section uses redundancies to flag misunderstandings of function interfaces in Linux. Certain functions, such as `kmalloc`, returns a `NULL` pointer on failure. Callers of these functions need to check the validity of their return values before they can safely dereference them. In prior work [11], we described an algorithm that automatically derives the set of potential `NULL`-returning functions in Linux. Here we use the logical opposite of that algorithm to flag functions whose return values should never be checked against

---

```

1 /* linux2.5.53/fs/ntfs/attrib.c:ntfs_merge_run_lists */
2 if (!slots) {
3     /* FIXME/TODO: We need to have the extra
4      * memory already! (AIA) */
5     drl = ntfs_rl_realloc(drl, ds, ds + 1);
6     if (!drl) /* BUG: drl is never NULL */
7         goto critical_error;
8 }

```

---

Fig. 14. Redundant NULL-check of `drl` signals a more serious problem: return values of `ntfs_rl_realloc` should in fact be checked with `IS_ERR`. A NULL-check will never catch the error case.

NULL. A naive view is that at worst such redundant checks are minor performance mistakes. In practice, we found they can flag two dangerous situations.

- 1) The programmer believes that a function can fail when it cannot. If they misunderstand the function’s interface at this basic level, they likely misunderstand other aspects.
- 2) The programmer correctly believes that a function can fail, but misunderstands how to check for failure. Linux and other systems have functions that indicate failure in some way other than returning a null pointer.

For each pointer-returning function  $f$  the checker tracks two counts:

- 1) The number of call sites where the pointer returned by  $f$  was checked against null before use.
- 2) The number of call sites where the returned pointer was not checked against null before use.

A function  $f$  whose result is often checked against NULL implies the belief that  $f$  could potentially return NULL. Conversely, many uses with few NULL checks implies the belief that the function should not be checked against NULL. We use the  $z$ -statistic [14] to rank functions from most to least likely to return NULL based on these counts. Return values from functions with highest  $z$ -values should probably be checked before use, whereas NULL-checks on those from the lowest ranked functions are most likely redundant.

Figure 14 shows one of the two bugs we found in a recent release of Linux. Here, the redundant NULL-check at line 6 signals the problem: the programmer has obviously misunderstood the interface to the function `ntfs_rl_realloc`, which, as shown below,

```

/* 2.5.53/fs/ntfs/attrib.c:ntfs_rl_realloc */
...
new_rl = ntfs_malloc_nofs(new_size);
if (unlikely(!new_rl))
    return ERR_PTR(-ENOMEM);
...

```

will never return NULL. Instead, on memory exhaustion, it will return what is essentially `((void*)-ENOMEM)`, which should be checked using the special `IS_ERR` macro. When `ntfs_rl_realloc` fails, the null check will fail too, and the code will dereference the returned value, which will likely correspond to a valid physical address, causing a very difficult-to-diagnose memory corruption bug. Unsurprisingly, the same bug appeared again at another location in this author’s code.

## VII. PREDICTING HARD ERRORS WITH REDUNDANCIES

In this section we show the correlation between redundant errors and hard bugs that can crash a system. The redundant errors are collected from the redundant assignment checker, the dead code checker, and the redundant conditional checker.<sup>3</sup> The hard bugs were collected from Linux 2.4.1 with checkers described in [8]. These bugs include use of freed memory, dereferences of null pointers, potential deadlocks, unreleased locks, and security violations (e.g., the use of an untrusted value as an array index). They have been reported to and largely confirmed by Linux developers. We show that there is a strong correlation between these two error populations using a statistical technique called the contingency table method [6]. Further, we show that a file containing a redundant error is roughly 45% to 100% more likely to have a hard error than one selected at random. These results indicate that (1) files with redundant errors are good audit candidates and (2) redundancy correlates with confused programmers who will probably make a series of mistakes.

### A. Methodology

This subsection describes the statistical methods used to measure the association between program redundancies and hard errors. Our analysis is based on the  $2 \times 2$  contingency table [6] method. It is a standard statistical tool for studying the association between two different attributes of a population. In our case, the population is the set of files we have checked in Linux, and the two attributes are: (a) whether a file contains redundancies, and (b) whether it contains hard errors.

In the contingency table approach, the population is cross-classified into four categories based on two attributes, say **A** and **B**, of the population. We obtain counts ( $o_{ij}$ ) in each category, and tabulate the results as follows:

A	B		Totals
	True	False	
True	$o_{11}$	$o_{12}$	$n_{1.}$
False	$o_{21}$	$o_{22}$	$n_{2.}$
Totals	$n_{.1}$	$n_{.2}$	$n_{..}$

The values in the margin ( $n_{1.}, n_{2.}, n_{.1}, n_{.2}$ ) are row and column totals, and  $n_{..}$  is the grand total. The null hypothesis  $H_0$  of this test is that **A** and **B** are mutually independent, i.e. knowing **A** gives no additional information about **B**. More precisely, if  $H_0$  holds, we expect that:

$$\frac{o_{11}}{o_{11} + o_{12}} \approx \frac{o_{21}}{o_{21} + o_{22}} \approx \frac{n_{.1}}{n_{.1} + n_{.2}}.$$

We can then compute expected values ( $e_{ij}$ ) for the four cells in the table as follows:

$$e_{ij} = \frac{n_{i.}n_{.j}}{n_{..}}$$

<sup>3</sup>We exclude the idempotent operation and redundant NULL-check results because the total number of bugs is too small to be statistically significant.

<sup>4</sup>To see this is true, consider 100 white balls in an urn. We first randomly draw 40 of them and put a red mark on them. We put them back in the urn. Then we randomly draw 80 of them and put a blue mark on them. Obviously, we should expect roughly 80% of the 40 balls with red marks to have blue marks, as should we expect roughly 80% of the remaining 60 balls without the red mark to have a blue mark.



We use a “chi-squared” test statistic [14]:

$$T = \sum_{i,j \in \{1,2\}} \frac{(o_{ij} - e_{ij})^2}{e_{ij}}$$

to measure how far the observed values ( $o_{ij}$ ) deviates from the expected values ( $e_{ij}$ ). Using the  $T$  statistic, we can derive the the probability of observing  $o_{ij}$  if the null hypothesis  $H_0$  is true. This probability is called the  $p$ -value.<sup>5</sup> The smaller the  $p$ -value, the stronger the evidence against  $H_0$ , thus the stronger the correlation between attributes **A** and **B**.

### B. Data acquisition and test results

In our previous work [8], we used the *xgcc* system to check 2055 files in Linux 2.4.1. These focused on serious system crashing hard bug and collected more than 1800 serious hard bugs in 551 files. The types of bugs we checked for included null pointer dereference, deadlocks, and missed security checks. We use these bugs to represent the class of serious hard errors, and derive correlation with program redundancies.

We cross-classify the program files in the Linux kernel into the following four categories and obtain counts in each:

- 1)  $o_{11}$ : number of files with both redundancies and hard errors.
- 2)  $o_{12}$ : number of files with redundancies but not hard errors.
- 3)  $o_{21}$ : number of files with hard errors but not redundancies.
- 4)  $o_{22}$ : number of files with neither redundancies nor hard errors.

We can then carry out the test described in section VII-A for the redundant assignment checker, dead code checker, and redundant conditional checker.

The result of the tests are given in Tables V through VIII. Note that in the aggregate case, the total number of redundancies is less than the sum of number of redundancies from each of the four checkers. That is because we avoid double counting files that are flagged by two or more checkers. As we can see, the correlation between redundancies and hard errors are extremely high, with  $p$ -values being approximately 0 in all four cases. The results strongly suggest that redundancies often signal confused programmers, and therefore are a good predictor for hard, serious errors.

### C. Predicting hard errors

In addition to the qualitative measure of correlation, we want to know quantitatively how much more likely it is that we will find hard errors in a file that contains one or more redundant operations. More precisely, let  $E$  be the event that a given source file contains one or more hard errors, and  $R$  be the event that it has one or more forms of redundant operations,

<sup>5</sup>Technically, under  $H_0$ ,  $T$  has a  $\chi^2$  distribution with one degree of freedom.  $p$ -value can be looked up in the cumulative distribution table of the  $\chi^2_1$  distribution. For example, if  $T$  is larger than 4, the  $p$ -value will go below 5%.

Redundant Assignments	Hard Bugs		Totals
	Yes	No	
Yes	345	435	780
No	206	1069	1275
Totals	551	1504	2055

$$T = 194.37, p\text{-value} = 0.00$$

TABLE V

CONTINGENCY TABLE: REDUNDANT ASSIGNMENTS VS. HARD BUGS. THERE ARE 345 FILES WITH BOTH ERROR TYPES, 435 FILES WITH A REDUNDANT ASSIGNMENTS AND NO HARD BUGS, 206 FILES WITH A HARD BUG AND NO REDUNDANT ASSIGNMENTS, AND 1069 FILES WITH NO BUGS OF EITHER TYPE. A  $T$ -STATISTIC VALUE ABOVE FOUR GIVES A  $p$ -VALUE OF LESS THAN 0.05, WHICH STRONGLY SUGGESTS THE TWO EVENTS ARE NOT INDEPENDENT. THE OBSERVED  $T$  VALUE OF 194.37 GIVES A  $p$ -VALUE OF ESSENTIALLY 0, NOTICEABLY BETTER THAN THE STANDARD THRESHOLD. INTUITIVELY, THE CORRELATION BETWEEN ERROR TYPES CAN BE SEEN IN THAT THE RATIO OF 345/435 IS CONSIDERABLY LARGER THAN THE RATIO 206/1069 — IF THE EVENTS WERE INDEPENDENT, WE EXPECT THESE TWO RATIOS TO BE APPROXIMATELY EQUAL.

Dead Code	Hard Bugs		Totals
	Yes	No	
Yes	133	135	268
No	418	1369	1787
Totals	551	1504	2055

$$T = 81.74, p\text{-value} = 0.00$$

TABLE VI

CONTINGENCY TABLE: DEAD CODE VS. HARD BUGS

we can compute a confidence interval for  $T' = (P(E|R) - P(E))/P(E)$ , which measures how much more likely we are to find hard errors in a file given the presence of redundancies.

The prior probability of hard errors is computed as follows:

$$P(E) = \frac{\text{Number of files with hard errors}}{\text{Total number of files checked}} = \frac{551}{2055} = 0.2681$$

We tabulate the conditional probabilities and  $T'$  values in Table IX. (Again, we excluded the idempotent operations and redundant NULL-checks because of their small bug sample.) As shown in the table, given presence of any form of redundant operation, it is roughly 45% – 100% more likely we will find an error in that file than in a randomly selected file.

Redundant Conditionals	Hard Bugs		Totals
	Yes	No	
Yes	75	79	154
No	476	1425	1901
Totals	551	1504	2055

$$T = 40.65, p\text{-value} = 0.00$$

TABLE VII

CONTINGENCY TABLE: REDUNDANT CONDITIONALS VS. HARD BUGS

R	$R \wedge E$	R	$P(E R)$	$P(E R) - P(E)$	Standard Error	95% Confidence Interval for $T'$
Assign	353	889	0.3971	0.1289	0.0191	48.11% $\pm$ 13.95%
Dead Code	30	56	0.5357	0.2676	0.0674	99.82% $\pm$ 49.23%
Conditionals	75	154	0.4870	0.2189	0.0414	81.65% $\pm$ 30.28%
Aggregate	372	945	0.3937	0.1255	0.0187	46.83% $\pm$ 13.65%

TABLE IX

PROGRAM FILES WITH REDUNDANCIES ARE ON AVERAGE ROUGHLY 50% MORE LIKELY TO CONTAIN HARD ERRORS

Aggregate	Hard Bugs		Totals
	Yes	No	
Yes	372	573	945
No	179	931	1110
Totals	551	1504	2055

 $T = 140.48$ ,  $p$ -value = 0.00

TABLE VIII

CONTINGENCY TABLE: PROGRAM REDUNDANCIES (AGGREGATE) VS. HARD BUGS

## VIII. DETECTING SPECIFICATION MISTAKES

This section describes how to use redundant code actions to find several types of specification errors and omissions. Often program specifications give extra information that allow code to be checked: whether return values of routines must be checked against NULL, which shared variables are protected by which locks, which permission checks guard which sensitive operations, etc. A vulnerability of this approach is that if a code feature is not annotated or included in the specification, it will not be checked. We can catch such omissions by flagging redundant operations. In the above cases, and in many others, at least one of the specified actions makes little sense in isolation — critical sections without shared states are pointless as are permission checks that do not guard known sensitive actions. Thus, if code does not intend to do useless operations, then such redundancies will happen exactly when checkable actions have been missed. (At the very least we will have caught something pointless that should be deleted.) We sketch four examples below, and close with two case studies that use redundancies to find missing checkable actions.

**Detecting omitted null annotations.** Tools such as Splint [12] let programmers annotate functions that can return a null pointer with a “null” annotation. The tool emits an error for any unchecked use of a pointer returned from a null routine. In a real system, many functions can return null, making it easy to forget to annotate them all. We can catch such omissions using redundancies. We know only the return value of null functions should be checked. Thus, a check on a non-annotated function means that either the function: (1) should be annotated with null or (2) the function cannot return null and the programmer has misunderstood the interface. A variant of this technique has been applied with success in [11], and also in the checker described in Section VI.

**Finding missed lock-variable bindings.** Data race detection tools such as Warlock [24] let users explicitly bind locks to the variables they protect. The tool warns when annotated

variables are accessed without their lock held. However, lock-variable bindings can easily be forgotten, causing the variable to be (silently) unchecked. We can use redundancies to catch such mistakes. Critical sections must protect *some* shared state: flagging those that do not will find either (1) useless locking (which should be deleted for better performance) or (2) places where a shared variable was not annotated.

**Missed “volatile” annotations.** As described in Section IV, in C, variables with unusual read/write semantics must be annotated with the “volatile” type qualifier to prevent the compiler from doing optimizations that are safe on normal variables, but incorrect on volatile ones, such as eliminating duplicate reads or writes. A missing volatile annotation is a silent error, in that the software will usually work, but only occasionally give incorrect results on certain hardware-compiler combinations. As shown, such omissions can be detected by flagging redundant operations (reads or writes) that do not make sense for non-volatile variables.

**Missed permission checks.** A secure system must guard sensitive operations (such as modifying a file or killing a process) with permission checks. A tool can automatically catch such mistakes given a specification of which checks protect which operations. The large number of sensitive operations makes it easy to forget a binding. As before, we can use redundancies to find such omissions: assuming programmers do not do redundant permission checks, finding permission check that does not guard a known sensitive operation signals an incomplete specification.

## A. Case study: Finding missed security holes

In a separate paper [3] we describe a checker that found operating system security holes caused when an integer read from untrusted sources (network packets, system call parameters) was passed to a trusting sink (array indices, length parameters in memory copy operations) without being checked against a safe upper and lower bound. A single violation can let a malicious attacker take control of the entire system. Unfortunately, the checker is vulnerable to omissions. An omitted source means the checker will not track the data produced. An omitted sink means the checker will not warn when unsanitized data reaches it.

When implementing the checker we used the ideas in this section to detect such omissions. Given a list of known sources and sinks, the normal checking sequence is: (1) the code reads data from an unsafe source, (2) checks it, and (3) passes it to a trusting sink. Assuming programmers do not do gratuitous sanitization, a missed sink can be detected by flagging when

code does steps (1) and (2), but not (3). Reading a value from a known source and sanitizing it implies the code believes the value will reach a dangerous operation. If the value does not reach a known sink, we have likely missed one in our specification. Similarly, we could (but did not) infer missed sources by doing the converse of this analysis: flagging when the OS sanitizes data we do not think is tainted and then passes it to a trusting sink.

The analysis found roughly 10 common uses of sanitized inputs in Linux 2.4.6 [3]. Nine of these uses were harmless; however one was a security hole. Unexpectedly, this was not from a specification omission. Rather, the sink was known, but our inter-procedural analysis had been overly simplistic, causing us to miss the path to it. The fact that redundancies flag errors both in the specification and in the tool itself was a nice surprise.

### B. Case study: Helping static race detection

We have developed a static race detection tool, RacerX [10], that has been dramatically improved by explicitly using the fact that programmers do not perform redundant operations.

At a high level, the tool is based on a static lockset algorithm similar to the dynamic version used in Eraser [23]. It works roughly as follows: (1) the user supplies a list of locking functions and a source base to check; (2) the tool compiles the source base and does a context-sensitive interprocedural analysis to compute the set of locks held at all program points; (3) RacerX warns when shared variables are used without a consistent lock held.

This simple approach needs several modifications to be practical. We describe two problems below that can be countered in part by using the ideas in this paper.

First, it is extremely difficult to determine if an unprotected access is actually an bug. Many unprotected accesses are perfectly acceptable. For example, programmers intentionally do unprotected modifications of statistics variables for speed, or they may orchestrate reads and writes of shared variables to be non-interfering (e.g., a variable that has a single reader and writer may not need locking). An unprotected access is only an error if it allows an application-specific invariant to be violated. Thus, reasoning about such accesses requires understanding complex code invariants and actual interleavings (rather than potential ones), both of which are often undocumented. In our experience, a single race condition report can easily take tens of minutes to diagnose. Even at the end it may not be possible to determine if the report is actually an error. In contrast, other types of errors found with static analysis often take seconds to diagnose (e.g., uses of freed variables, not releasing acquired locks).

We can simplify this problem using a form of redundancy analysis. The assumption that programmers do not write redundant critical sections, implies that the first, last, and only shared data accesses in a critical section are special:

- If a variable or function call is the only statement within the critical section, we have very strong evidence that the programmer thinks (1) the state should be protected

```

1  /* ERROR: linux-2.5.62/drivers/char/esp.c:
2  *   2313:block_til_ready: calling <serial_out-info>
3  *   without "cli()"!
4  */
5  restore_flags(flags); /* re-enable interrupts */
6  set_current_state(TASK_INTERRUPTIBLE);
7  if (tty_hung_up_p(filp)
8  || !(info->flags & ASYNC_INITIALIZED)) {
9      ...
10 }
11
12 /* non-disabled access to serial_out-info! */
13 serial_out(info, UART_ESI_CMD1, ESI_GET_UART_STAT);
14 if (serial_in(info, UART_ESI_STAT2) & UART_MSR_DCD)
15     do_clocal = 1;
16 ...
17
18 /* Example 1 drivers/char/esp.c:1206 */
19 save_flags(flags); cli();
20 /* set baud */
21 serial_out(info, UART_ESI_CMD1, ESI_SET_BAUD);
22 serial_out(info, UART_ESI_CMD2, quot >> 8);
23 serial_out(info, UART_ESI_CMD2, quot & 0xff);
24 restore_flags(flags);
25 ...
26
27
28 /* Example 2: drivers/char/esp.c:1426 */
29 cli();
30 info->IER &= ~UART_IER_RDI;
31 serial_out(info, UART_ESI_CMD1, ESI_SET_SRV_MASK);
32 serial_out(info, UART_ESI_CMD2, info->IER);
33 serial_out(info, UART_ESI_CMD1, ESI_SET_RX_TIMEOUT);
34 serial_out(info, UART_ESI_CMD2, 0x00);
35 sti();

```

Fig. 15. Error ranked high because of redundancy analysis: there were 28 places where the routine `serial_out` was used as the first or last statement in a critical section.

in general and (2) that the acquired lock enforces this protection.

- Similarly, the first and last accesses of shared states in a critical section also receive special treatment (although to a lesser degree), since programmers often acquire a lock on the first shared state access that must be protected and release it immediately after the last one—i.e., they do not gratuitously make critical sections large.

A crucial result of these observations is that displaying such examples of where a variable or function was explicitly protected makes it very clear to a user of RacerX what exactly is being protected. Figure 15 gives a simple example of this from Linux. There were 37 accesses to `serial_out` with some sort of lock held, in contrast there was only one unlocked use. This function-argument pair was the first statement of a critical section 11 times and the last one 17 times. Looking at the examples it is obvious that the programmer is explicitly disabling interrupts<sup>6</sup> before

<sup>6</sup>`cli()` clears the Interrupt Enable Flag on x86 architectures, thus it prevents preemption, and has the effect of acquiring a global kernel lock on single processor systems. `sti()` and `restore_flags(flags)` restores the Interrupt Enable Flag. They can be thought of as releasing the kernel lock previously acquired by `cli()`.

invoking this routine. In particular we do not have to look at the implementation of `serial_out` and try to reason about whether it or the device it interacts with needs to be protected with disabled interrupts. In practice we almost always look at errors that have such features over those that do not.

A second problem with static race detection is that many seemingly multi-threaded code paths are actually single-threaded. Examples include operating system interrupt handlers and initialization code that runs before other threads have been activated [23]. Warnings for accesses to shared variables on single-threaded code paths can swamp the user with false positives, at the very least hiding real errors and in the worse case causing the user to discard the tool.

This problem can also be countered using redundancy analysis. We assume that in general programmers do not do spurious locking. We can thus infer that any concurrency operation implies that the calling code is multithreaded. These operations include locking, as well as calls to library routines that provide atomic operations such as `atomic_add` or `test_and_set`. (From this perspective, concurrency calls can be viewed as carefully inserted annotations specifying that code is multithreaded.)

RacerX considers any function to be multithreaded if concurrency operations occur (1) anywhere within the function, or (2) anywhere above it in the call chain<sup>7</sup>. Note that such operations below the function may not indicate the function itself is multithreaded. For example, it could be calling library code that always conservatively acquires locks. RacerX computes the information for (1) and (2) in two passes. First, it walks over all functions, marking them as multithreaded if they do explicit concurrency operations within the function body. Second, when doing the normal lockset computation it also tracks if it has hit a known multithreaded function. If so, it adds this annotation to any error emitted.

Finally, static checkers have the invidious problem that errors in their analysis often cause silent false negatives. Redundancy analysis can help find these: critical sections that contain no shared states imply that either the programmer made a mistake or the analysis did. We found eight errors in the RacerX implementation when we modified the tool to flag empty critical sections. There were six minor errors, one error where we mishandled arrays (and so ignored all array uses indexed by pointer variables) and a particularly nasty silent lockset caching error that caused us to miss over 20% of all code paths.

## IX. RELATED WORK

In writing the five redundancy checkers, we leverage heavily from existing research on program redundancy detection and elimination. Techniques such as partial redundancy elimination [18], [20], [21] and dead code elimination algorithms [1], [17], [19] have long been used in optimizing compilers to reduce code size and improve program performance. While our analyses closely mirror these ideas at their core,

there are two key differences that distinguish our approach to that used in optimizing compilers:

- 1) Optimizers typically operate on a low-level intermediate representation (IR) with a limited set of primitive operations on typeless pseudo-registers. In contrast, our analyses need to operate at the source level and work with (or around) the full-blown semantic complexity of C. The reason is three-fold: a) many redundant operations are introduced in the translation from source constructs to intermediate representations, making it hard to distinguish ones that pre-exist in the source program; b) useful diagnostic information such as types (e.g. `unsigned` vs. `signed`) and variable or macro names (e.g. `DEBUG`) are typically discarded during the translation to IR—we find such information essential in focused suppression of false positives; c) the translation to IR usually changes the source constructs so much that reporting sensible warning messages at the IR level is extremely difficult, if not impossible.
- 2) While being sound and conservative is vital in optimizing compilers, error detection tools like ours can afford (and are often required) to be flexible for the sake of usefulness and efficiency. The redundant NULL checker in Section VI harvests function interface specifications from a statistical analysis of their usage patterns. Although the analysis is effective, it is neither sound nor conservative, and therefore would most likely not be admissible in optimizers.
- 3) Compilers are typically invoked far more frequently than checking tools during the development cycle. Therefore, speed is essential for the analyses being used in the optimizer. Expensive path-sensitive algorithms are carried out sparingly, if at all, on small portions of performance critical code simply because their time complexity usually outweighs their benefit. In contrast, checking tools like ours are less frequently run and can therefore afford to use more expensive analyses. The redundant conditional checker is one such example. The less stringent speed requirement does give us a substantial edge in detecting more classes of errors with more accuracy.

Redundancy analyses have also been used in existing checking tools. Fosdick and Osterweil first applied data flow *anomaly detection* techniques in the context of software reliability. In their DAVE system [22], they used a depth first search algorithm to detect a set of variable def-use type of anomalies such as uninitialized read, double definition, etc. However, according to our experiments, path insensitive analysis like theirs produces an overwhelming number of false positives, especially for the uninitialized read checker. We were unable to find experimental validations of their approach to make a meaningful comparison.

Recent releases of the GNU C compiler (version 3 and up) provides users with the “`-Wunreachable-code`” option to detect dead code in the source program. However, their analysis provides no means of controlled suppression of false positives, which we find essential in limiting the number of

<sup>7</sup>Since RacerX is a static tool, we approximate this information by a simple reachability analysis on the static call graph.

false warnings. Also, because of its recent inception, the dead code detection algorithm is not yet fully functional<sup>8</sup> as of this writing.

Dynamic techniques [7], [16] instrument the program and detects anomalies that arise during execution. However, they are weaker in that they can only find errors on executed paths. Furthermore, the run-time overhead and difficulty in instrumenting low-level operating system code limits the applicability of dynamic approaches. The effectiveness of the dynamic approach is unclear because of the lack of experimental results.

Finally, some of the errors we found overlap with ones detected by other non-redundant checkers. For example, Splint [12] warns about fall-through `case` branches in `switch` statements even when they do not cause redundancies. It could have (but did not) issued a warning for the error shown in Figure 4.<sup>9</sup> However, many if not most of the errors we find (particularly those in Section V and Section VI) are not found by other tools and thus seem worth investigating. Unfortunately we cannot do a more direct comparison to Splint because it lacks experimental data and we were unable to use it to compile the programs we check.

## X. CONCLUSION

This paper explored the hypothesis that redundancies, like type errors, flag higher-level correctness mistakes. We evaluated the approach using five checkers which we applied to the Linux, OpenBSD, and PostgreSQL. These simple analyses found many surprising (to us) error types. Further, they correlated well with known hard errors: redundancies seemed to flag confused or poor programmers who were prone to other errors. These indicators could be used to identify low-quality code in otherwise high-quality systems and help managers choose audit candidates in large code bases.

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<sup>8</sup>One sample error in the GCC analysis is reported at <http://gcc.gnu.org/ml/gcc-prs/2003-03/msg01359.html>.

<sup>9</sup>Apparently the parser was having trouble understanding the code and did not get far enough to check the problem part of the program.

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